

# Amplification of the magnetic field by r-mode instability: Role of the back-reaction

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# CFS instability: Instability due to emission of GW waves

Uniform rotation => Minimal energy for given angular momentum  $J$   $E_{\text{rot}}(J); \quad \delta E_{\text{rot}} = \Omega \delta J$

Excitation energy  $E_{\text{ex}} = E - E_{\text{rot}} > 0$

Gravitational radiation:  $-\frac{\omega}{m} j^{\text{GW}} = \dot{E}^{\text{GW}} < 0$   
[Thorne 1980]

$$\dot{E}_{\text{ex}}^{\text{GW}} = \dot{E}^{\text{GW}} - \dot{E}_{\text{rot}}^{\text{GW}} = -\left(\frac{\omega}{m} + \Omega\right) j^{\text{GW}} = \frac{\omega + m\Omega}{\omega} \dot{E}^{\text{GW}}$$

Increase of excitation energy  $\dot{E}_{\text{ex}}^{\text{GW}} > 0 \Rightarrow$  instability

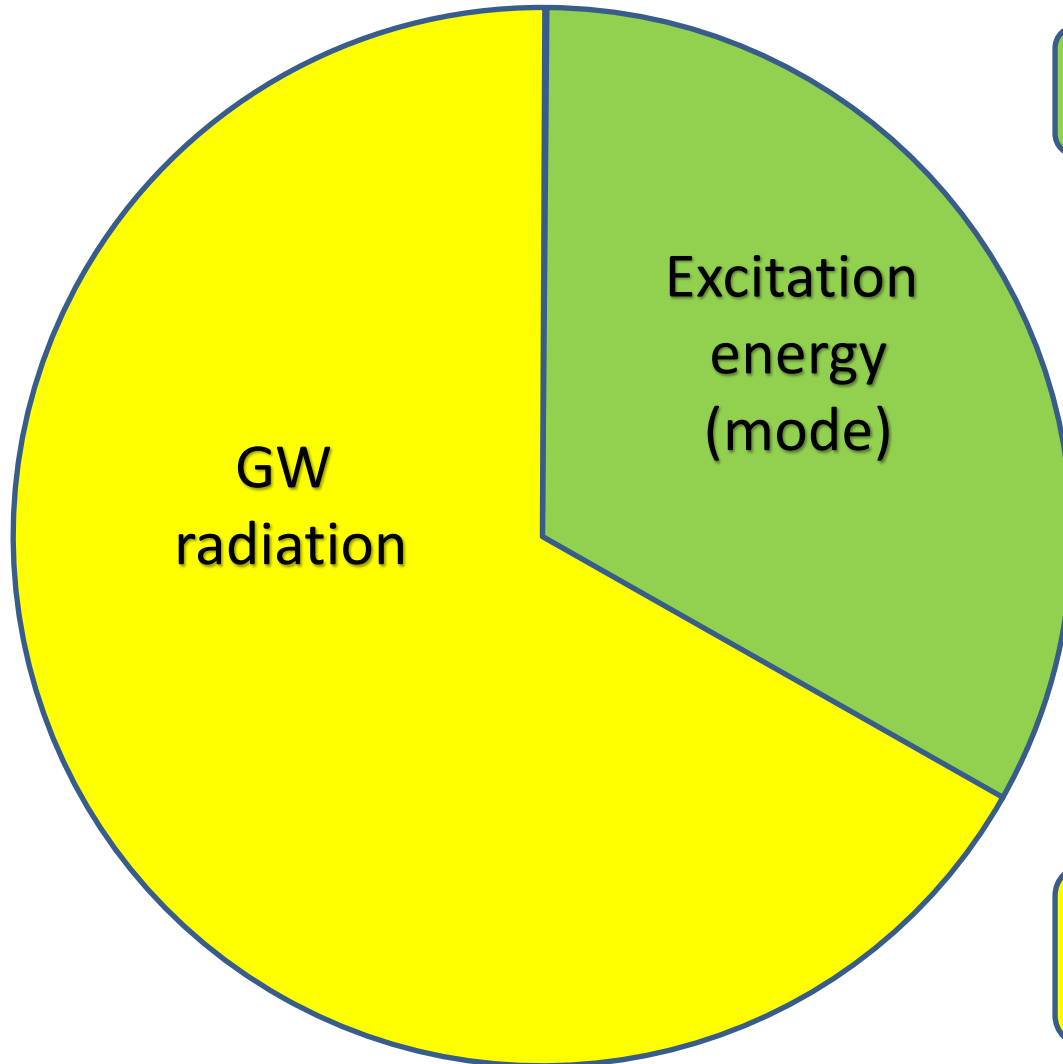
CFS instability criteria:  $\omega + m\Omega > 0; \omega < 0$   
[Friedman&Schutz (1978a,b)]

The energy source is the rotation energy  $\dot{E}_{\text{ex}}^{\text{GW}} + \left| \dot{E}^{\text{GW}} \right| = \left| \dot{E}_{\text{rot}}^{\text{GW}} \right|$

# CFS-instability energy budget

Income: decrease of rotational energy,  $\left| \dot{E}_{\text{rot}}^{\text{GW}} \right|$

Expenses: emission of GW radiation  $L^{\text{GW}}$ , enhancement of the mode  $\dot{E}_{\text{ex}}^{\text{GW}}$



$$\dot{E}_{\text{ex}}^{\text{GW}} = \left( 1 + \frac{\omega}{m\Omega} \right) \left| \dot{E}_{\text{rot}}^{\text{GW}} \right| > 0$$

Perturbations  $\propto \sin(m\phi + \omega t)$

$$\omega + m\Omega > 0; \omega < 0$$

$$L^{\text{GW}} + \dot{E}_{\text{ex}}^{\text{GW}} = \left| \dot{E}_{\text{rot}}^{\text{GW}} \right|$$

$$L^{\text{GW}} \equiv -\dot{E}^{\text{GW}} = -\frac{\omega}{m\Omega} \left| \dot{E}_{\text{rot}}^{\text{GW}} \right|$$

# R-mode instability: key features

m=2 R-modes:  $\omega = -\frac{4}{3}\Omega$   $\delta^{(1)}\mathbf{v} = \alpha R\Omega \left(\frac{r}{R}\right)^2 \mathbf{Y}_{22}^B \exp^{i\omega t}$   
[Provost et al. 1981]

CFS instability criteria:  $\omega + m\Omega > 0; \omega < 0$   
[Friedman&Schutz (1978a,b)]

Instability at any rotation rate (in absence of dissipation)

[Andresson 1998, Friedman&Morsink 1998]

Dissipation suppress r-mode instability at low spin frequency, but it can strongly affect evolution of rapidly rotating NSs (e.g., limit its spin frequency)

[Bildsten 1998, Andresson et al. 1999, Levin 2000...]

## Observations vs theory

Observations put strong constraints to the suppression of the r-mode instability, but the mechanism of this suppression is still not well established (e.g., shear viscosity in npe-matter is not enough)

[Haskell et al. 2012, Haskell 2015, Schwenzer et al. 2017, AIC et al. 2017,.... ]

# R-mode instability and magnetic windup

Magnetic damping of r-modes:

[Rezzolla et al. 2000-2001]

- r-modes are likely to be accompanied by differential drift of fluid elements
- Differential drift amplify magnetic field
- Enhancement of magnetic field removes energy from r-modes => r-mode instability might be prevented or suppressed

Key question of this talk:

Does this mechanism actually work in neutron stars?

Yes

R-mode instability can generate magnetic field, but after that NS should be r-mode stable.

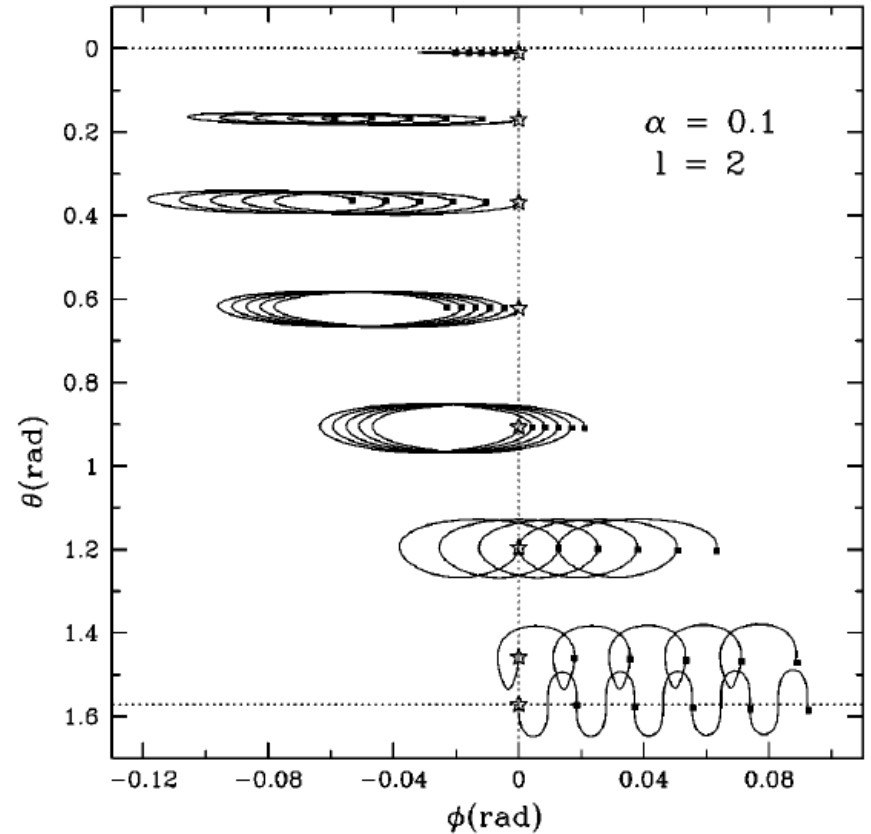
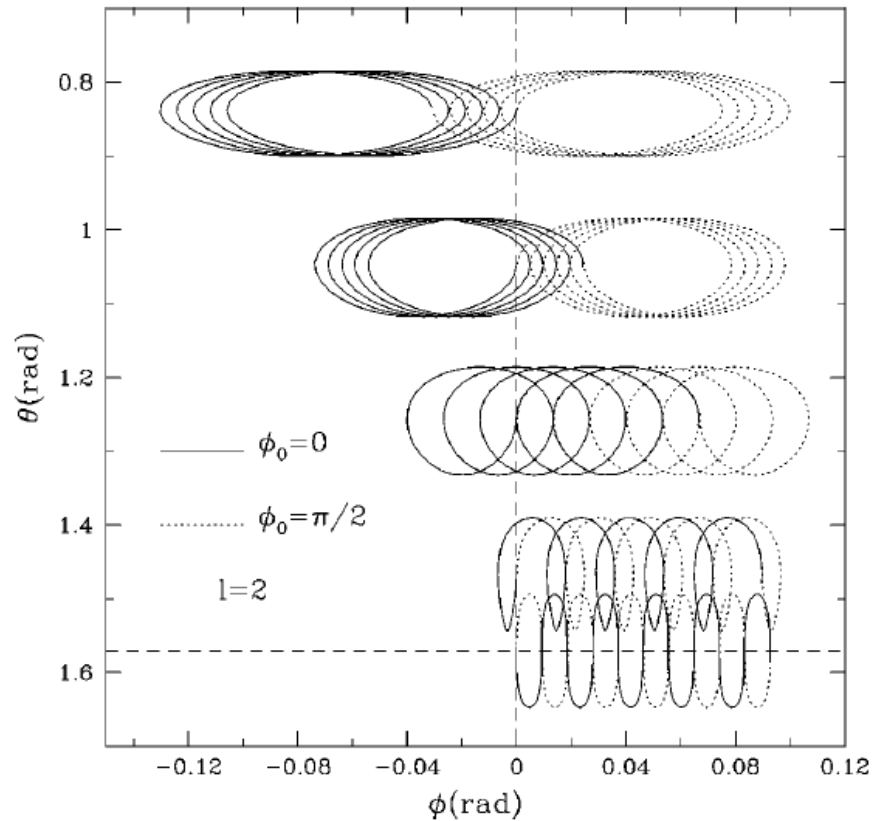
No problems with r-modes, but **no detailed information on NSs**

No

Other mechanism of suppression of the r-mode instability is required, leading thus to **constraints to the (micro)physics of NSs**

Rezzolla et al. (2001a):

# Differential drift of fluid elements enhance magnetic field



$$\frac{\partial B}{\partial t} = [\nabla \times [\mathbf{v} \times \mathbf{B}]]$$

Magnetic field is winded up and enhanced

$$\mathbf{v} = \delta^{(1)} \mathbf{v}$$



Secular increase of magnetic field

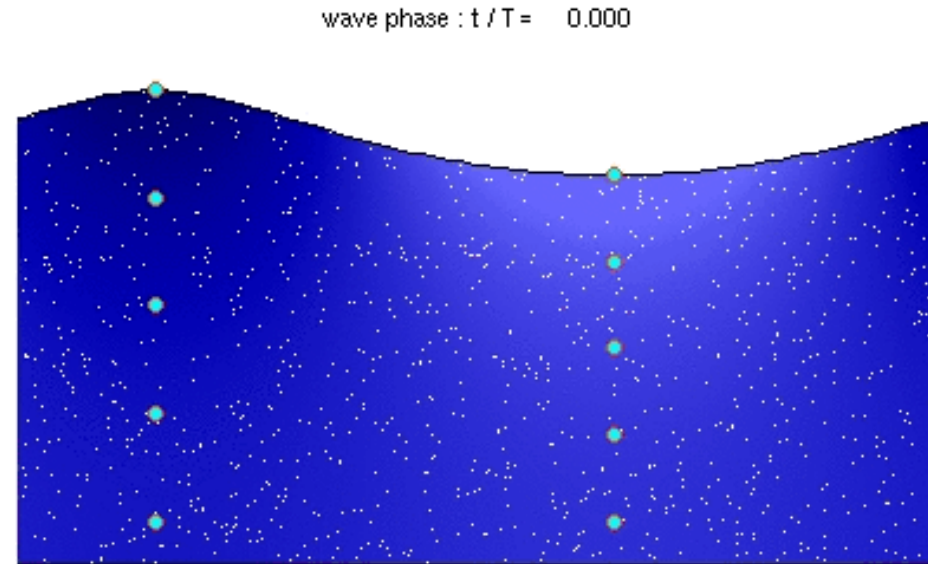
$$\Delta B \propto \alpha^2 t$$

# Stokes drift

*G.G. Stokes (1847). "On the theory of oscillatory waves". Transactions of the Cambridge Philosophical Society 8: 441–455*

Wikipedia:

For a pure [wave motion](#) in [fluid dynamics](#), the **Stokes drift velocity** is the [average velocity](#) when following a specific [fluid](#) parcel as it travels with the [fluid flow](#).



(from wikipedia)

## Main features of Stokes drift:

- Second order in amplitude
- Even if time averaged Eulerian velocity (even at every point) is (exactly) zero, macroscopic drift of fluid elements can take place
- This drift is not correction to the Eulerian velocity field

# Stokes drift and Eulerian velocity profile

## Second order perturbation theory

Eulerian velocity:  $v = \epsilon v_1 + \epsilon^2 v_2 + \dots; \quad \epsilon \ll 1$

Velocity of the fluid element, which was at coordinate  $x_0$  at the moment  $t=0$ :

$$V(x_0, t) = v \left( x_0 + \int_0^t V dt, t \right) \approx v(x_0, t) + \int_0^t V dt \cdot \nabla v(x_0, t)$$

$$V = \epsilon V_1 + \epsilon^2 V_2 + \dots$$

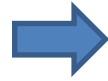
$$\bar{V}_1 = \bar{v}_1; \quad \bar{V}_2 = \bar{v}_2 + \overline{\int_0^t v_1 dt \cdot \nabla v_1}$$

Stokes drift is NOT the only contribution to secular drift



# R-mode instability and (differential) second order rotation

Rotation energy acts as energy source for instability



Physical angular momentum should decrease  $\delta J < 0$

$$\mathbf{J} = \int \rho [\mathbf{r} \times \mathbf{v}] dV$$

$$\delta \mathbf{J} = \mathbf{J} - \mathbf{J}_0$$

$$\delta \rho = O(\Omega^2) = o(\Omega)$$



$$\delta^{(i)} \mathbf{J} = \int \rho [\mathbf{r} \times \delta^{(i)} \mathbf{v}] dV$$

$$\delta^{(1)} v \propto \exp(im\phi)$$



$$\delta^{(1)} \mathbf{J} = 0; \quad \delta^{(2)} \mathbf{J} = \int \rho [\mathbf{r} \times \delta_{sym}^{(2)} \mathbf{v}] dV$$

$\delta_{sym}^{(2)} \mathbf{v} \neq 0$  is essential for instability, but should **drift** be differential?  
(fixed  $\delta J$  does not fix velocity perturbation profile and thus drift profile)

Is differential drift essential for Newtonian r-modes (no GW radiation)?

# Newtonian r-modes at the second order in amplitude

[Sa, Phys. Rev. D **69** (2004), 084001]

$$\partial_t \delta^{(1)} v_i + \delta^{(1)} v^k \nabla_k v_i + v^k \nabla_k \delta^{(1)} v_i = -\nabla_i \delta^{(1)} U,$$

$$\partial_t \delta^{(1)} \rho + v^i \nabla_i \delta^{(1)} \rho + \nabla_i (\rho \delta^{(1)} v^i) = 0,$$

$$\Delta \delta^{(1)} \Phi = 4\pi G \delta^{(1)} \rho,$$

$$\delta^{(i)} U = \delta^{(i)} (p/\rho) + \delta^{(i)} \Phi$$

$$\partial_t \delta^{(2)} v_i + \delta^{(2)} v^k \nabla_k v_i + v^k \nabla_k \delta^{(2)} v_i + \delta^{(1)} v^k \nabla_k \delta^{(1)} v_i$$

$$= -\nabla_i \delta^{(2)} U + \frac{\delta^{(1)} \rho}{\rho} \nabla_i \left( \frac{\delta^{(1)} p}{p} \right),$$

$$\partial_t \delta^{(2)} \rho + v^i \nabla_i \delta^{(2)} \rho + \nabla_i (\rho \delta^{(2)} v^i)$$

$$+ \nabla_i (\delta^{(1)} \rho \delta^{(1)} v^i) = 0,$$

$$\Delta \delta^{(2)} \Phi = 4\pi G \delta^{(2)} \rho.$$

Induced by the first order solution

# Newtonian r-modes at the second order in amplitude

[Sa, Phys. Rev. D **69** (2004), 084001]

$$\begin{aligned}\partial_t \delta^{(2)} v_i &+ \delta^{(2)} v^k \nabla_k v_i + v^k \nabla_k \delta^{(2)} v_i + \delta^{(1)} v^k \nabla_k \delta^{(1)} v_i \\ &= -\nabla_i \delta^{(2)} U + \frac{\delta^{(1)} \rho}{\rho} \nabla_i \left( \frac{\delta^{(1)} p}{p} \right), \\ \partial_t \delta^{(2)} \rho &+ v^i \nabla_i \delta^{(2)} \rho + \nabla_i (\rho \delta^{(2)} v^i) \\ &+ \nabla_i (\delta^{(1)} \rho \delta^{(1)} v^i) = 0, \\ \Delta \delta^{(2)} \Phi &= 4\pi G \delta^{(2)} \rho.\end{aligned}$$

## Crucial properties

- General second order solution = partial solution + general solution of homogeneous equations (i.e., it is not unique)
- Homogeneous equations are the same as equation for linear perturbations in nonoscillating star

# Newtonian r-modes: drift velocity

[Chugunov, MNRAS **451**, 2772–2779 (2015)]

$$(v^{(d)})^\phi = \alpha^2 \Omega f(\varpi)$$

$$\varpi = r \sin(\theta)$$

Drift velocity is a solution of linearized equations:  
arbitrary (differential) rotation, stratified on cylinders.  
Cylindrical layers are decoupled and moves independently.

**Differential drift can be absent**

# Newtonian NS: Drift and oscillations are decoupled

[Chugunov, MNRAS **451**, 2772–2779 (2015)]

Drift and oscillations are independent degrees of freedom:

General second order r-mode solution: superposition of

(a) oscillating solution with *vanishing drift*

(b) *drift*

Secular evolution of magnetic field is coupled only with drift

$$B = 0$$

Oscillating solution with vanishing drift exists

Drift: Arbitrary stationary motion of cylindrical layers

$$B \neq 0$$

Oscillating solution with vanishing drift is unaffected by  $B$ , if  $B \ll 10^{16}$  G

Drift & magnetic field evolves as in nonoscillating star (Alfven waves + uniform rotation).

R-mode energy is conserved. Magnetic damping is absent

# Effect of gravitational radiation-reaction force

In absence of magnetic field: exponentially increasing of mode amplitude and displacement of fluid elements [Friedman et al., 2016]

$$\alpha = \alpha_0 \exp(\beta t)$$

R-mode energy density:  $\mathcal{E}_{mode} \sim \rho [\alpha \Omega R]^2$

Drift:

$$\langle \dot{\phi}(t) \rangle \approx -\frac{3}{2} \alpha^2(t) \Omega \left[ \frac{\varpi^2}{4} + \Upsilon(\varpi) \right]; \quad \varpi = r \sin(\theta)$$

Drift is cylindrically stratified, but differential.

As far as cylindrical layers are decoupled it is not surprising

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Magnetic field: Couples cylindrical layers at the Alfvén timescale

$$\tau_A \equiv \omega_A^{-1} = R / \sqrt{B^2 / (4\pi\rho)}$$

# Effect of gravitational radiation-reaction force

Magnetic field: Couples cylindrical layers at the Alfvén timescale

$$\omega_A^2 = \frac{B^2}{4\pi\rho R^2}$$

Heuristic approach: oscillator under action of external force

$$\ddot{x} + \omega_A^2 x = f, \quad x = R\xi^\phi$$

$$\xi_{\max}^\phi = \phi(t) - \phi(0) \sim \frac{|f_{\max}|}{R\omega_A^2}$$

External force (per unit mass): axisymmetric part of gravitational radiation-reaction force [Friedman et al., PRD 93 (2016), 024023]

+ second order magnetic terms [Friedman et al., to be submitted].

It can be estimated as

$$f_{\max} \lesssim \alpha^2 \omega_A \Omega R \quad \longrightarrow \quad \xi_{\max}^\phi \lesssim \alpha^2 \frac{\Omega}{\omega_A}$$

# Effect of gravitational radiation-reaction force

Magnetic field: Couples cylindrical layers at the Alfvén timescale

$$\omega_A^2 = \frac{B^2}{4\pi\rho R^2}$$

Displacement: oscillator under action of external force

$$\xi_{\max}^{\phi} \lesssim \alpha^2 \frac{\Omega}{\omega_A}$$

Magnetic field, generated by the drift:

$$\delta B \sim B_0 \xi^{\phi} \lesssim \alpha_{\text{sat}}^2 B_0 \frac{\Omega}{\omega_A}$$



# Effect of gravitational radiation-reaction force

Magnetic field: Couples cylindrical layers at the Alfvén timescale

$$\omega_A^2 = \frac{B^2}{4\pi\rho R^2}$$

Displacement: oscillator under action of external force

$$\xi_{\max}^{\phi} \lesssim \alpha^2 \frac{\Omega}{\omega_A}$$

Energy density of generated magnetic field (=energy of the oscillator)

$$\mathcal{E}_m \sim \rho\omega_A^2 (R\xi^{\phi})^2 \sim \alpha^2 \mathcal{E}_{mode} \ll \mathcal{E}_{mode}$$

Mode energy density  $\mathcal{E}_{mode} \sim \rho [\alpha \Omega R]^2$



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Strict mathematical derivation via second order Lagrangian perturbation theory:  
Friedman et al. (to be submitted)

## Summary

- The generated magnetic field is strongly limited

$$\delta B \lesssim \alpha_{\text{sat}}^2 B_0 \Omega / \omega_A$$

For example,  $10^{11}$  G can be generated from  $10^9$  G if  $\alpha_{\text{sat}} \sim 10^{-3}$

- Increase of magnetic energy can not suppress r-mode instability

$$\mathcal{E}_m \sim \alpha^2 \mathcal{E}_{\text{mode}} \ll \mathcal{E}_{\text{mode}}$$

### Take away messages:

- The magnetic damping can not suppress r-mode instability in case of low saturation amplitude
- Mechanism of r-mode instability suppression is required by observations, but it is still not well established. Solution of this problem can put tight constraints to physics of NSs [not limited by mass-radius curve, see, e.g., poster 20 by Kantor et al.].